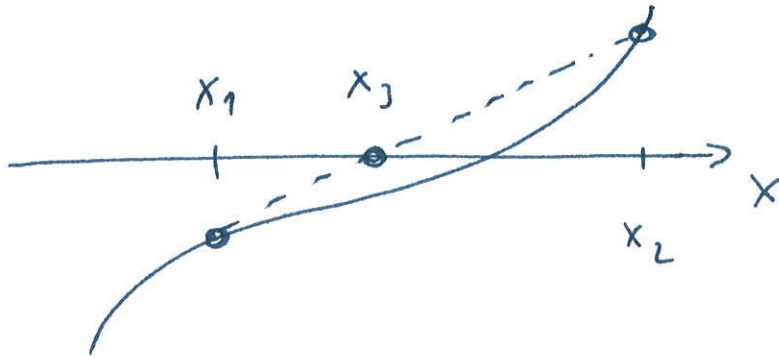


Sečny - lineární interpolace



$$\frac{x_2 - x_3}{f(x_2) - 0} = \frac{x_2 - x_1}{f(x_2) - f(x_1)}$$

$$x_2 - x_3 = f(x_2) \frac{x_2 - x_1}{f(x_2) - f(x_1)}$$

$$x_3 = x_2 - f(x_2) \frac{x_2 - x_1}{f(x_2) - f(x_1)}$$

Ridders

$$x_1, x_2, x_3 = \frac{x_1 + x_2}{2}$$

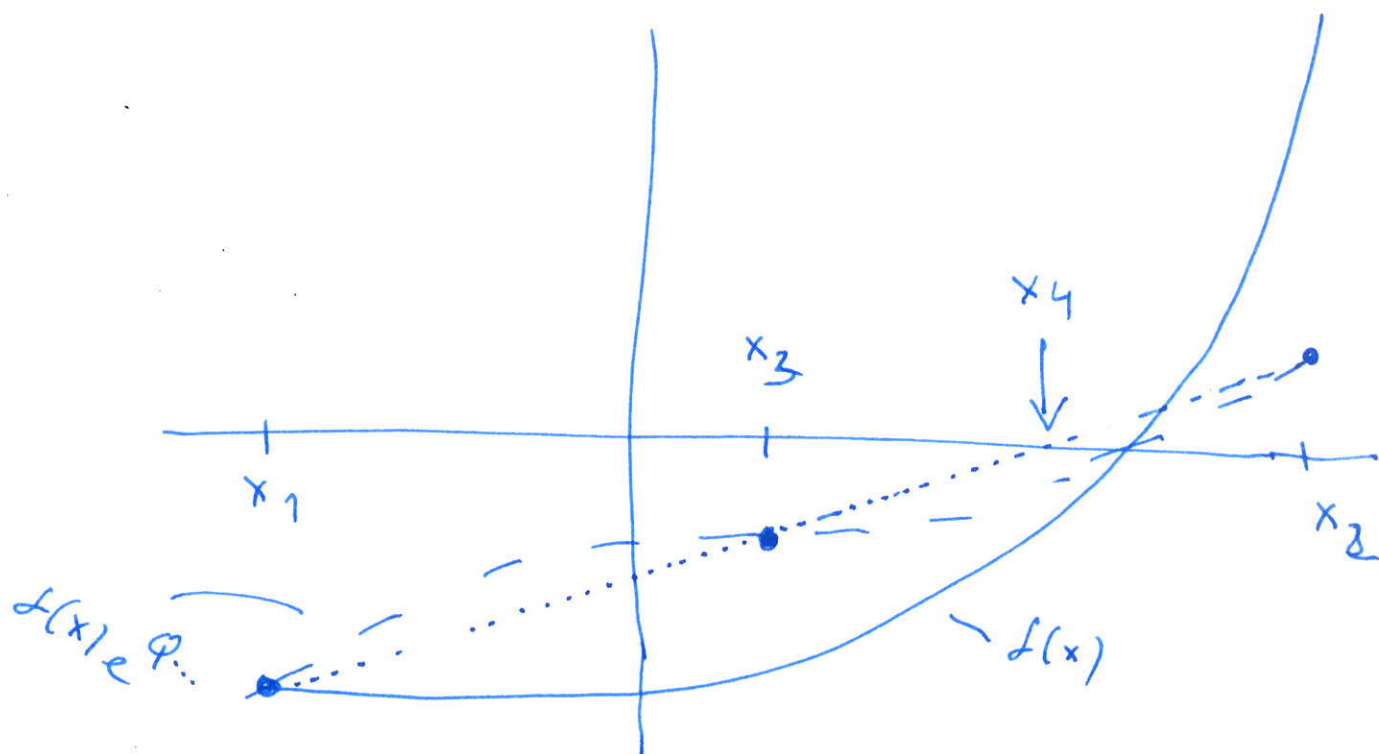
odstranění ohybu

$$f(x) \rightarrow f(x) e^Q \frac{x-x_1}{x_3-x_1} \quad (\text{zachová kořeny})$$

$$\text{tj. } f(x_1), f(x_2) \rightarrow f(x_2) e^{2Q}, f(x_3) \rightarrow f(x_3) e^Q$$

linearizace

$$\frac{f(x_1) + f(x_2) e^{2Q}}{2} = f(x_3) e^Q$$



Convergence Newton-Raphson

rozvoj $f(x)$ kolem kořene $f(x_0) = 0$

$$f(x_0 + \epsilon) = 0 + \epsilon f'(x_0) + \epsilon^2 \frac{f''(x_0)}{2}$$

$$f'(x_0 + \epsilon) = f'(x_0) + \epsilon f''(x_0)$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

n -tá iterace N-R

$$x_n = x_0 + \epsilon_n$$

$$x_{n+1} = x_0 + \epsilon_{n+1}$$

$$\epsilon_{n+1} = \epsilon_n - \frac{f(x_n)}{f'(x_n)} = \epsilon_n - \frac{\epsilon_n f'(x_0) + \epsilon_n^2 \frac{f''(x_0)}{2}}{f'(x_0) \left[1 + \epsilon_n \frac{f''(x_0)}{f'(x_0)} \right]}$$

$$\approx \epsilon_n - \left[\epsilon_n + \epsilon_n^2 \frac{f''(x_0)}{2f'(x_0)} \right] \left[1 - \epsilon_n \frac{f''(x_0)}{f'(x_0)} \right]$$

$$\approx \epsilon_n^2 \frac{f''(x_0)}{2f'(x_0)}$$

Newton - Raphson (soustav)

$$f_i(x_1 + \delta x_1, x_2 + \delta x_2, \dots, x_N + \delta x_N)$$

$$\equiv f_i(x_1, x_2, \dots, x_N) + \sum_j \underbrace{\frac{\partial f_i(x_1, x_2, \dots, x_N)}{\partial x_j}}_{J_{ij}} \delta x_j$$

$$J_{ij} \equiv \frac{\partial f_i}{\partial x_j}$$

$$f_i(\vec{x} + \vec{\delta x}) = f_i(\vec{x}) + \sum_j J_{ij}(\vec{x}) \delta x_j$$

$$= f_i(\vec{x}) + (J \vec{\delta x})_i$$

$$\vec{f}'(\vec{x} + \vec{\delta x}) = \vec{f}'(\vec{x}) + J(\vec{x}) \vec{\delta x}$$